Primer in Matrix Algebra

Giulio Rossetti[∗]

giuliorossetti94.github.io

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∗ email: giulio.rossetti.1@wbs.ac.uk

What is a Matrix?

- A matrix is a rectangular set of numbers (i.e., range in Excel).
- Example:

$$
A = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}
$$

• Vectors are special cases of matrices with only one column:

$$
x = \begin{bmatrix} a \\ c \\ e \end{bmatrix}
$$

Matrix Addition

• Add matrices by adding corresponding elements:

$$
A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}, \quad A + B = \begin{bmatrix} a+e & b+f \\ c+g & d+h \end{bmatrix}
$$

• Matrices must have the same shape to add.

Matrix Multiplication

- Multiply matrices by combining rows of the left matrix with columns of the right matrix.
- Example:

$$
A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}, \quad B = \begin{bmatrix} g & h \\ i & j \\ k & l \end{bmatrix}
$$

$$
AB = \begin{bmatrix} ag + bi + ck & ah + bj + cl \\ dg + ei + fk & dh + ej + fl \end{bmatrix}
$$

• Matrices must have compatible dimensions.

Properties of Matrix Multiplication

- Distributive property: $(A + B)C = AC + BC$
- Non-commutative: $AB \neq BA$

• Identity matrix:
$$
I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
$$
 satisfies $AI = IA = A$.

Transpose and Symmetric Matrices

• Transpose: Swap rows and columns of a matrix.

$$
A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad A' = \begin{bmatrix} a & c \\ b & d \end{bmatrix}
$$

• Symmetric matrix: $A = A'$.

$$
A = \begin{bmatrix} a & d & e \\ d & b & f \\ e & f & c \end{bmatrix}
$$

Matrix Operations

• Element-wise multiplication and division:

$$
A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad A = \begin{bmatrix} e & f \\ g & h \end{bmatrix}
$$

$$
A \cdot * B = \begin{bmatrix} ae & bf \\ cg & dh \end{bmatrix}, \quad A./B = \begin{bmatrix} \frac{a}{e} & \frac{b}{f} \\ \frac{c}{g} & \frac{d}{h} \end{bmatrix}
$$

Inner, Outer, and Quadratic Forms

• Inner product: A row vector times a column vector gives a scalar.

$$
x'y = \begin{bmatrix} a & b & c \end{bmatrix} \begin{bmatrix} d \\ e \\ f \end{bmatrix} = ad + cf + be
$$

• Outer product: A column vector times a row vector gives a matrix.

$$
xy' = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \begin{bmatrix} d & e & f \end{bmatrix} = \begin{bmatrix} ad & ae & af \\ bd & be & bf \\ cd & ce & cf \end{bmatrix}
$$

Inner, Outer, and Quadratic Forms *Cont'd*

• Quadratic form: Combines a vector, a symmetric matrix, and another vector.

$$
x'Ax = \begin{bmatrix} e & f \end{bmatrix} \begin{bmatrix} a & b \\ b & d \end{bmatrix} \begin{bmatrix} e \\ f \end{bmatrix} = ae^2 + df^2 + 2bef
$$

Matrix Inversion

- Inverse of *A*: A^{-1} satisfies $AA^{-1} = A^{-1}A = I$.
- Conditions for inversion:
	- *A* must be square.
	- *A* must have full rank.
- Example:

$$
\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}
$$

Applications of Matrices

Linear Regression

Roadmap:

- Linear regression model in matrix form
- Minimization problem
- Derivation of OLS estimate

• The linear regression model is:

$$
Y=X\beta+\epsilon
$$

• Expanded notation:

$$
\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ \vdots & \vdots \\ x_{N1} & x_{N2} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_N \end{bmatrix}
$$

- If there is a constant in the regression, the first column of *X* is all 1s.
- OLS estimate:

$$
\hat{\beta} = (X'X)^{-1}X'Y
$$

- Where does $\hat{\beta} = (X'X)^{-1}X'Y$ come from?
- Sum of squared residuals:

$$
RSS = \sum_{i}^{N} \epsilon_i^2 = \epsilon' \epsilon = (Y - X\beta)'(Y - X\beta)
$$

• Minimize RSS with respect to *β*:

$$
\hat{\beta} = \arg\min_{\beta} \epsilon' \epsilon
$$

=
$$
\arg\min_{\beta} (Y - X\beta)'(Y - X\beta)
$$

=
$$
\arg\min_{\beta} Q(\beta)
$$

• rewrite *Q*(*β*):

$$
Q(\beta) = (y - X\beta)'(y - X\beta),
$$

$$
= (y' - \beta'X')(y - X\beta), \quad \text{since } (X\beta)' = \beta'X',
$$

$$
= y'y - \beta'X'y - y'X\beta + \beta'X'X\beta,
$$

$$
= y'y - 2y'X\beta + \beta'X'X\beta, \quad \text{since } \beta'X'y = y'X\beta.
$$

• differentiate¹ $Q(\beta)$ with respect to β

$$
\left. \frac{\partial Q(\beta)}{\partial \beta'} \right|_{\beta = \hat{\beta}} = -2(X'y)' + 2\hat{\beta}'X'X.
$$

• FOC: set the *k* vector of partial derivatives to zero:

$$
-2(X'y)' + 2\hat{\beta}'X'X = 0'_{K+1}
$$

• rewrite the FOC:

1 *∂*(*a*

$$
X'X\hat{\beta} = X'y
$$

$$
\hat{\beta} = (X'X)^{-1}X'y
$$

$$
\hat{\beta} = (X'X)^{-1}X'y
$$

$$
\hat{\beta} = (X'X)^{-1}X'y
$$