

# Seminar 7: Heteroskedasticity, Collinearity & Unit Roots

*SLR Assumptions, Dickey-Fuller Tests, and Error Correction Models*

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## Disclaimer

Full solutions are available on my.wbs. All exercises are examinable material, not just the ones we covered in the seminars.

# Roadmap

Exercise 1: Heteroskedasticity in SLR

Exercise 2: Perfect Collinearity in MLR

Exercise 3: Dickey-Fuller Unit Root Test

Exercise 4: Error Correction Model

Exercise 5: ADF Test for U.S. Inflation

Exercise 6: ADF Test for Log U.S. Real GDP

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# Why Does This Matter?

## Motivation

OLS relies on key assumptions about the error term. Understanding *when* these assumptions hold – and when they don't – is essential for valid inference.

In this exercise we explore a savings function where:

- The zero conditional mean assumption (SLR.4) is satisfied
- But the homoskedasticity assumption (SLR.5) is violated

**Key idea:** The error variance depends on income – richer people have more variable savings.

# Exercise 1: The Savings Function $\text{var}(ax|Y) = a^2 \text{var}(x|Y)$

Consider the savings function:

$$\text{sav} = \beta_0 + \beta_1 \text{inc} + u \quad u = \sqrt{\text{inc}} \cdot e$$

where  $e$  is a random variable with  $\underline{E[e]} = 0$  and  $\underline{\text{Var}[e]} = \sigma_e^2$ . Assume  $e$  is independent of  $\text{inc}$ .

Part (a): Show that  $E[u | \text{inc}] = 0$  (SLR.4 is satisfied).  $e \perp \text{inc}$

Part (b): Show that  $\text{Var}(u | \text{inc}) = \sigma_e^2 \cdot \text{inc}$  (SLR.5 is violated).

$$E[u | \text{inc}] = E[\sqrt{\text{inc}} \cdot e | \text{inc}] = \sqrt{\text{inc}} E[e | \text{inc}] = \sqrt{\text{inc}} E[e] = 0$$

$$\text{var}(u | \text{inc}) = \text{var}(\sqrt{\text{inc}} \cdot e | \text{inc}) = \text{inc} \cdot \text{var}(e | \text{inc}) = \text{inc} \cdot \text{var}(e) = \text{inc} \cdot \sigma_e^2$$

## Solution: Zero Conditional Mean (SLR.4)

When we condition on  $inc$ , the term  $\sqrt{inc}$  becomes a constant:

$$E[u \mid inc] = E[\sqrt{inc} \cdot e \mid inc] = \sqrt{inc} \cdot E[e \mid inc]$$

Since  $e$  is independent of  $inc$ , we have  $E[e \mid inc] = E[e] = 0$ , so:

$$E[u \mid inc] = 0$$

**Intuition:** Independence of  $e$  from  $inc$  ensures that the error has no systematic relationship with income. The  $\sqrt{inc}$  scaling doesn't change this because it only affects the *spread*, not the *average*.

## Solution: Heteroskedasticity (SLR.5 Violated)

Again, conditioning on  $inc$  makes  $\sqrt{inc}$  a constant in the variance:

$$\text{Var}[u \mid inc] = \text{Var}[\sqrt{inc} \cdot e \mid inc] = inc \cdot \text{Var}[e \mid inc] = inc \cdot \sigma_e^2$$

$$\boxed{\text{Var}(u \mid inc) = \sigma_e^2 \cdot inc}$$

**Intuition:** The variance of savings **increases with income**. This makes sense: higher-income individuals have more discretion in how much they save, leading to more variable savings behaviour.

**Consequence:** OLS is still **unbiased** (SLR.4 holds), but the usual standard errors are **incorrect**. Use heteroskedasticity-robust standard errors.

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## Exercise 2: The GPA Model

Students report weekly hours in four activities: *study*, *sleep*, *work*, *leisure*. Consider:

$$\rightarrow GPA = \beta_0 + \beta_1 \text{study} + \beta_2 \text{sleep} + \beta_3 \text{work} + \beta_4 \text{leisure} + u$$

$$\text{study} + \text{sleep} + \text{work} + \text{leisure} = 168$$

Question: Does it make sense to hold *sleep*, *work*, and *leisure* fixed while changing *study*?

$$\text{leisure} = 168 - \text{study} - \text{sleep} - \text{work}$$

$$\hat{\beta} = \underbrace{(x'x)^{-1}} x'y$$

# Solution: The Constraint Problem

**No.** By definition:

$$study + sleep + work + leisure = 168$$

If we change *study*, at least one other variable **must** change to maintain the sum.

## Which assumption is violated?

- We can write:  $study = 168 - sleep - work - leisure$
- This is a **perfect linear function** of the other regressors
- This holds for every observation  $\Rightarrow$  violates **MLR.3** (no perfect collinearity)

## Solution: How to Fix It

Simply drop one variable, say *leisure*:

$$\rightarrow GPA = \beta_0 + \beta_1 \text{study} + \beta_2 \text{sleep} + \beta_3 \text{work} + u \quad \beta_1: \uparrow \text{study} \downarrow \text{leisure}$$

$$\rightarrow GPA = \beta_0 + \beta_1 \text{study} + \beta_2 \text{sleep} + \beta_3 \text{leisure} + u$$

$\beta_1: \uparrow \text{study} \downarrow \text{work}$

### Interpretation of $\beta_1$ :

- The change in GPA when *study* increases by one hour, holding *sleep*, *work*, and *u* fixed
- If *sleep* and *work* are fixed but *study* goes up by 1 hour, then *leisure* must go down by 1 hour
- So  $\beta_1$  measures the effect of trading one hour of leisure for one hour of study

# Roadmap

Exercise 1: Heteroskedasticity in SLR

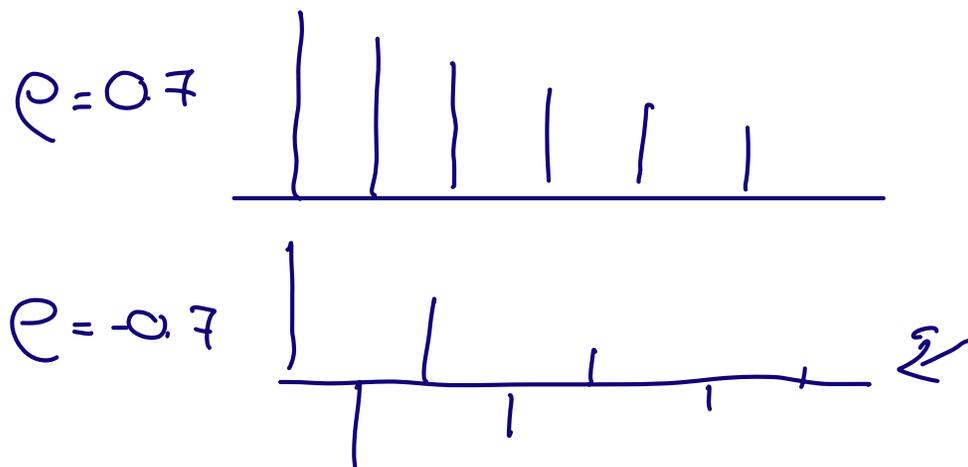
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$$\text{RW: } X_t = \mu + X_{t-1} + \varepsilon_t \quad \varepsilon_t \sim N(0, \sigma^2_\varepsilon)$$
$$\text{I}(1) \quad X_t - X_{t-1} = \mu + \varepsilon_t \Rightarrow \Delta X_t = \mu + \varepsilon_t$$

# Exercise 3: Testing for a Unit Root in T-Bill Rates

We want to test whether three-month T-bill rates  $r_{3t}$  contain a unit root.

Step 1: Start with an AR(1) model:

$$\Rightarrow \left\{ \begin{array}{l} H_0: |\rho| = 1 \rightarrow \text{nonstationarity} \\ H_1: |\rho| < 1 \rightarrow \text{stationarity} \end{array} \right.$$

$$\rightarrow r_{3t} = \mu + \rho r_{3t-1} + \epsilon_t, \quad \epsilon_t \sim N(0, \sigma^2)$$

$I(1) \quad I(1)$

Step 2: Subtract  $r_{3t-1}$  from both sides:

$$\rightarrow \Delta r_{3t} = \mu + (\rho - 1) r_{3t-1} + \epsilon_t = \mu + \theta r_{3t-1} + \epsilon_t$$

$I(0) \quad \theta \quad I(1)$

where  $\theta = \rho - 1$ .

$$\Delta r_{3t} = \mu + \theta r_{3t-1} + \epsilon_t$$

$\nearrow$  run reg  $\rightarrow \hat{\theta}$   
stat  $\frac{\hat{\theta}}{se(\hat{\theta})} \sim DF$

nonstationarity

$$H_0: \theta = 0 \Rightarrow (\rho - 1) = 0 \Rightarrow \rho = 1$$

$$H_1: \theta < 0 \rightarrow \text{stationarity}$$

# The Dickey-Fuller Test

## Hypotheses:

- $H_0 : \theta = 0$  (unit root  $\Leftrightarrow \rho = 1$ )
- $H_1 : \theta < 0$  (stationary  $\Leftrightarrow |\rho| < 1$ )

**Intuition:** If  $\theta = 0$ , the series has no tendency to revert to any level – it “wanders” randomly. If  $\theta < 0$ , the series is pulled back toward its mean.

Can we use standard  $t$ -tests?

**No!** Under  $H_0$  (unit root), the usual  $t$ -statistic does not follow a normal distribution, even asymptotically. We must use the Dickey-Fuller critical values instead.

# Takeaway: Dickey-Fuller Test

## Key Points

- The DF test reparameterises the AR(1) so that  $H_0 : \theta = 0$  tests for a unit root
- Under  $H_0$ , standard  $t$ -tables are *invalid* – use DF critical values
- The test is *one-sided* (left-tail): reject  $H_0$  if the test statistic is sufficiently negative
- Critical values depend on whether you include a constant, trend, or neither

# Roadmap

Exercise 1: Heteroskedasticity in SLR

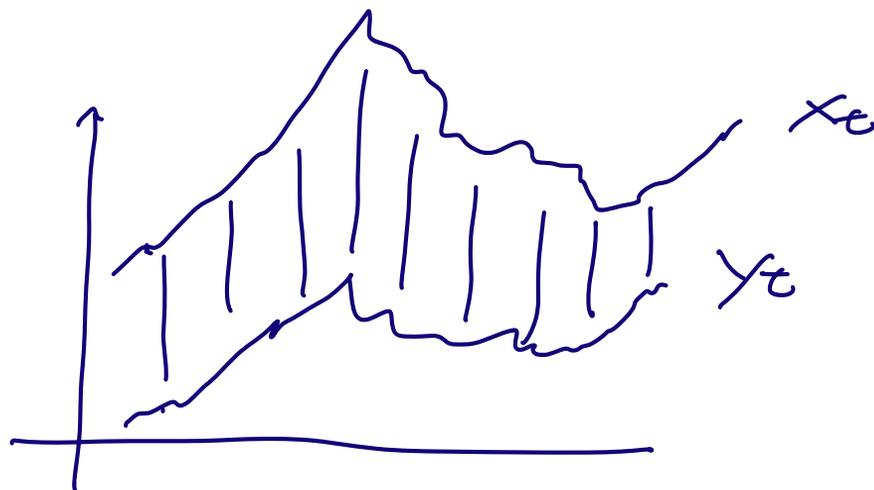
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# Motivation

## Definition (Cointegration).

Two variables  $x_t$  and  $y_t$  are cointegrated if

$$y_t = \beta x_t + z_t$$

residuals

$$z_t = y_t - \beta x_t$$

$$x_t, y_t \sim I(1) \quad \text{and} \quad \exists \beta \neq 0 \text{ such that } z_t = y_t - \beta x_t \sim I(0)$$

## Implication.

The linear combination

$$y_t = \beta x_t + u_t, \quad u_t \sim I(0)$$

is stationary. Deviations from the relation are therefore mean-reverting.

## Interpretation.

the spread  $y_t - \beta x_t$  cannot drift arbitrarily far and tends to return toward its mean. If  $x_t$  and  $y_t$  are cointegrated, they admit an Error Correction Model

## Exercise 4: Setup

Suppose  $\{(x_t, y_t)\}$  satisfies:

$$y_t = \beta x_t + u_t \quad \text{and} \quad \Delta x_t = \gamma \Delta x_{t-1} + \nu_t \quad \leftarrow$$

where  $E[u_t | I_{t-1}] = E[\nu_t | I_{t-1}] = 0$ ,  $\beta \neq 0$ ,  $|\gamma| < 1$ .

Goal: Show these imply an error correction model:

ECM

$$\Delta y_t = \underbrace{\gamma_1 \Delta x_{t-1}}_{\text{SR}} + \underbrace{\delta (y_{t-1} - \beta x_{t-1})}_{\text{LR}} + e_t$$

where  $\gamma_1 = \beta\gamma$ ,  $\delta = -1$ ,  $e_t = \beta\nu_t + u_t$ .

## Solution: Step 1 – Express $\Delta y_t$

Start from  $y_t = \beta x_t + u_t$  and subtract  $y_{t-1}$ :

$$\Delta y_t = \beta x_t - \underline{y_{t-1}} + u_t + \beta x_{t-1} - \beta x_{t-1}$$

Step 2: Add and subtract  $\beta x_{t-1}$ :

$$\Delta y_t = \beta \Delta x_t - \overbrace{(y_{t-1} - \beta x_{t-1})} + u_t$$

This isolates the error correction term  $(y_{t-1} - \beta x_{t-1})$ , which measures last period's deviation from the long-run equilibrium.

## Solution: Step 2 – Substitute $\Delta x_t$

Plug in  $\Delta x_t = \gamma \Delta x_{t-1} + \nu_t$ :

$$\begin{aligned}\Delta y_t &= \beta(\gamma \Delta x_{t-1} + \nu_t) - (y_{t-1} - \beta x_{t-1}) + u_t \\ &= \underbrace{\beta\gamma}_{\gamma_1} \Delta x_{t-1} - \underbrace{(y_{t-1} - \beta x_{t-1})}_{\delta} + \underbrace{(\beta\nu_t + u_t)}_{e_t}\end{aligned}$$

Identifying the components:

ECM

$$\Delta y_t = \underbrace{\beta\gamma}_{\gamma_1} \Delta x_{t-1} + \underbrace{\delta}_{-1} (y_{t-1} - \beta x_{t-1}) + \underbrace{e_t}_{\beta\nu_t + u_t}$$

**Intuition:**  $y_t$  adjusts due to (i) lagged changes in  $x$  (short-run dynamics) and (ii) last period's equilibrium error (error correction, with  $\delta = -1$  meaning full correction each period).

# Interpreting the Error Correction Model

**Short-run dynamics:**  $\gamma_1 \Delta x_{t-1}$

captures how recent changes in  $x_t$  affect current changes in  $y_t$ .

Example: if  $\gamma_1 = 0.4$ , a one-unit increase in  $\Delta x_{t-1}$  raises  $\Delta y_t$  by 0.4 units.

**Error correction term:**  $\delta(y_{t-1} - \beta x_{t-1})$  ←

The term  $y_{t-1} - \beta x_{t-1}$  measures the deviation from the long-run relation.

The coefficient  $\delta$  determines how quickly the system moves back toward equilibrium.

- If  $\delta < 0$ , deviations are corrected over time. ←
- The magnitude of  $\delta$  measures the speed of adjustment.

Example: if  $\delta = \underline{-0.3}$  and the spread  $y_{t-1} - \beta x_{t-1} = 10$ ,  $\Delta y_t = -3$  so about 30% of the disequilibrium is corrected in one period.

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# Why Does This Matter?

## Motivation

Is U.S. inflation stationary or does it contain a unit root? The answer matters for modelling and forecasting. The [Augmented Dickey-Fuller \(ADF\)](#) test handles serial correlation in the errors by including lagged differences.

$$\begin{array}{l} \text{DF} \quad \Delta x_t = \mu + \theta x_{t-1} + \varepsilon_t \\ \text{ADF} \quad \Delta x_t = \mu + \theta x_{t-1} + \gamma_1 \Delta x_{t-1} + \varepsilon_t \end{array}$$

## Exercise 5: ADF Specification for Inflation

Using annual U.S. inflation data (1948–1996), estimate:

$$\rightarrow \Delta y_t = \alpha + \theta y_{t-1} + \gamma_1 \Delta y_{t-1} + e_t$$

where  $|\gamma_1| < 1$ .

**Why “augmented”?** The extra  $\Delta y_{t-1}$  term absorbs serial correlation in the errors, ensuring the test statistic has the correct distribution.

**Hypotheses:** Same as DF —  $H_0 : \theta = 0$  (unit root) vs  $H_1 : \theta < 0$  (stationary).

# Exercise 5: Results and Interpretation

## Conceptual approach:

1. Construct  $\Delta y_t, y_{t-1}, \Delta y_{t-1}$  from the inflation data
2. Run OLS on the ADF regression
3. Compute the  $t$ -statistic for  $\hat{\theta}$
4. Compare with DF critical values (with constant, no trend)

**Result:** The DF 5% critical value is  $-2.86$ .

**Conclusion:** We reject the unit root hypothesis at the 5% level – inflation appears to be stationary.

**Caveat:** The sample is small ( $T \approx 47$ ), which reduces the power of the test. Small samples make it harder to distinguish a unit root from a near-unit-root process.

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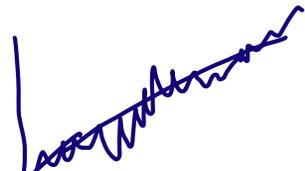
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## Exercise 6: ADF with Trend for Log GDP

For log real GDP, include a **time trend** because GDP has a clear upward trajectory:

$$\Delta y_t = \alpha + \delta t + \theta y_{t-1} + \gamma_1 \Delta y_{t-1} + e_t$$

**Why include a trend?** Log GDP trends upward over time. Without the trend term, the test would confuse the deterministic trend with a stochastic trend (unit root).

## Exercise 6: Results and Interpretation

### Conceptual approach:

1. Take logs of real GDP, construct differences and lags
2. Run OLS on the ADF regression with trend
3. Compute  $t$ -statistic for  $\hat{\theta}$
4. Compare with DF critical values (with constant *and* trend)

**Result:** The DF 5% critical value (with trend) is  $-3.41$ ; the 10% value is  $-3.12$ .

**Conclusion:** We fail to reject the unit root hypothesis at both the 5% and 10% levels – log real GDP is consistent with having a unit root.

**Caveat:** Again, sample size is small ( $T \approx 37$ ). The test has low power to distinguish between a unit root and a highly persistent but stationary process.

# Summary

## Key Takeaways

1. **Heteroskedasticity:** The error variance can depend on regressors even when  $E[u | x] = 0$ . Use robust standard errors.
2. **Perfect collinearity:** Exact linear relationships among regressors make OLS impossible. Drop one variable.
3. **Dickey-Fuller test:** Reparameterise AR(1) to test  $\theta = 0$ . Standard  $t$ -tables are invalid — use DF critical values.
4. **ECM:** Cointegrated variables adjust through both short-run dynamics and long-run error correction.
5. **ADF test:** Include lagged differences to handle serial correlation. Include a trend when the data has a deterministic trend.

# Key Formulas

Concept	Formula
Heteroskedasticity	$\text{Var}(u   x) = \sigma_e^2 \cdot x$
DF test regression	$\Delta y_t = \mu + \theta y_{t-1} + \epsilon_t$
ADF (with lag)	$\Delta y_t = \alpha + \theta y_{t-1} + \gamma_1 \Delta y_{t-1} + e_t$
ADF (with trend)	$\Delta y_t = \alpha + \delta t + \theta y_{t-1} + \gamma_1 \Delta y_{t-1} + e_t$
ECM	$\Delta y_t = \gamma_1 \Delta x_{t-1} + \delta (y_{t-1} - \beta x_{t-1}) + e_t$

$|e| = 1$       rw

$|e| \neq 1$

$|e| \geq 1$     explodes

$$\theta = (e - 1)$$

↑

$$e = 1 \quad \Rightarrow \quad \theta = 0$$

$e < 1$

