

Seminar 7 Solutions

Giulio Rossetti*

giuliorossetti94.github.io

February 28, 2025

* email: giulio.rossetti.1@wbs.ac.uk

Disclaimer

Full solutions are available on my.wbs. All exercises are examinable material, not just the ones we covered in the seminars.

Roadmap

Exercise 1

Exercise 2

Exercise 3

Exercise 4

Exercise 1: Simple Linear Regression (SLR) Model

Consider the savings function:

$$sav = \beta_0 + \beta_1 inc + \underline{u}, \quad u = \sqrt{inc} \cdot \underline{e} \quad \underline{E[e] = 0} \quad \text{Var}[e] = \underline{\sigma_e^2}$$

Assume that e is independent of inc. $e \perp\!\!\!\perp inc$

Show that the zero conditional mean assumption is satisfied.

$$E[u|x] = 0$$

$$E[u|inc] = 0$$

$$= E[\sqrt{inc} \cdot e | inc]$$

$$= \sqrt{inc} E[e | inc]$$

$$= \sqrt{inc} E[\underline{e}] = \sqrt{inc} \cdot 0 = 0$$

Homoskedasticity

$$\hookrightarrow \text{var}(u|x) = \sigma^2 \quad \sigma^2 > 0$$

$$\begin{aligned} \text{var}(u|inc) &= \text{var}(-\sqrt{inc} e | inc) \\ &= inc \text{var}(e | inc) \\ &= inc \text{var}(e) = \underline{inc \sigma_e^2} \end{aligned}$$

Derivation

- When we condition on inc , \sqrt{inc} becomes a **constant**.
- Therefore:

$$E[u|inc] = E[\sqrt{inc} \cdot e|inc] = \sqrt{inc}E[e|inc]$$

- Since $E[e|inc] = E[e] = 0$, it follows that:

$$E[u|inc] = 0.$$

Exercise 1: Violation of Homoskedasticity

Show that the homoskedasticity assumption SLR.5 is violated; that is,
 $\text{Var}(u|inc) = \sigma_e^2 inc$.

- Computing the conditional variance:

$$\text{Var}[u|inc] = \text{Var}[\sqrt{inc} \cdot e|inc]$$

- Since variance operators allow constants to be factored out:

$$\begin{aligned}\text{Var}[u|inc] &= inc \cdot \text{Var}[e|inc] \\ &= inc \cdot \sigma_e^2.\end{aligned}$$

- This shows that variance depends on inc , violating the homoskedasticity assumption.

Roadmap

Exercise 1

Exercise 2

Exercise 3

Exercise 4

Exercise 2: Multiple Linear Regression (MLR) Model

$$\begin{array}{c} \uparrow \\ \Rightarrow \text{study} + \text{sleep} + \text{work} + \text{leisure} = 168 \\ \downarrow \end{array}$$

Model

$$\text{study} = 168 - \text{sleep} - \text{work} - \text{leisure}$$

$$GPA = \beta_0 + \beta_1 \text{study} + \beta_2 \text{sleep} + \beta_3 \text{work} + \beta_4 \text{leisure} + u$$

does it make sense to hold *sleep*, *work*, and *leisure* fixed, while changing *study*?

- No. By definition, $\text{study} + \text{sleep} + \text{work} + \text{leisure} = 168$.
- If we change *study*, at least one other category must also change to maintain the total sum.

Violations of Gauss-Markov Assumptions

- *study* is a perfect linear combination of other regressors. This holds for every observation, violating MLR.3.

$$study = 168 - sleep - work - leisure.$$

How to fix this?

- Drop one of the independent variables, say *leisure*:

$$GPA = \beta_0 + \beta_1 study + \beta_2 sleep + \beta_3 work + u.$$

- β_1 : change in GPA when *study* increases by one hour, holding *sleep*, *work*, and *u* constant.
- If *sleep* and *work* are fixed but *study* \uparrow , then *leisure* \downarrow by one hour.

Roadmap

Exercise 1

Exercise 2

Exercise 3

Exercise 4

Dickey Fuller Test

r_{3t} has a unit root $\Rightarrow r_{3t}$ non-stationary

AR(1)

$$r_{3t} = \mu + \boxed{\rho} r_{3t-1} + \varepsilon_t \quad \varepsilon_t \sim N(0, \sigma_\varepsilon^2)$$

$\hookrightarrow |\rho| = 1 \Rightarrow RW$, nonstationary

$H_0: |\rho| = 1$ non stationarity

$H_1: |\rho| < 1$ stationarity

$$r_{3t} - r_{3t-1} = \mu + (\rho - 1)r_{3t-1} + \varepsilon_t$$

$$\Rightarrow \Delta r_{3t} = \mu + \underline{\theta} r_{3t-1} + \varepsilon_t$$

$\hookrightarrow I(0)$

$H_0: \theta = 0$

$RW \leftarrow$

$H_1: \theta < 0$

stationarity

$t_\theta < D_{Fu} \Rightarrow \text{reject}$

$\rho_1 \Delta r_{t-1} + \rho_2 \Delta r_{t-2} \dots$

$H_0:$

$r_{3t} \sim I(1)$

\downarrow

$\Delta r_{3t} \Rightarrow I(0)$

Roadmap

Exercise 1

Exercise 2

Exercise 3

Exercise 4

Exercise 4: Error Correction Model

$$\begin{matrix} \Delta y_t & I(0) \\ \Delta x_t & I(0) \end{matrix}$$

$$\Delta y_t = \alpha + \Delta x_t + \varepsilon_t$$

Suppose that the process $\{(x_t, y_t) : t = 0, 1, 2, \dots\}$ satisfies the equations:

$$\begin{matrix} x_t & I(1) \\ y_t & I(1) \end{matrix}$$

$$\rightarrow y_t = \beta x_t + u_t$$

$$\textcircled{1} y_t - y_{t-1} = \beta x_t - y_{t-1} + \varepsilon_t$$

and

$$\Delta x_t = \gamma \Delta x_{t-1} + \nu_t,$$

where:

- $E[u_t | I_{t-1}] = E[\nu_t | I_{t-1}] = 0$,
- I_{t-1} contains information on x and y dated at time $t - 1$ and earlier,
- $\beta \neq 0$, and $|\gamma| < 1$ (so that x_t , and therefore y_t , is $I(1)$).

Exercise 4: Error Correction Model

Show that the given equations imply an **error correction model**:

$$\longrightarrow \Delta y_t = \gamma_1 \Delta x_{t-1} + \delta(y_{t-1} - \beta x_{t-1}) + e_t,$$

where:

$$\gamma_1 = \beta\gamma, \quad \delta = -1, \quad e_t = \beta\nu_t + u_t.$$

Step 1: Expressing Δy_t

Start by subtracting y_{t-1} from both sides of $y_t = \beta x_t + u_t$:

$$\begin{aligned} I(0) \quad \Delta y_t &= \beta x_t - y_{t-1} + u_t. \\ &= \beta x_t - \beta x_{t-1} + \beta x_{t-1} - y_{t-1} + u_t \end{aligned}$$

$$\begin{aligned} \underbrace{\Delta y_t}_{I(0)} &= \beta \underbrace{\Delta x_t}_{I(0)} - y_{t-1} + u_t \\ &\quad \searrow \Delta x_t = \rho \Delta x_{t-1} + v_t \end{aligned}$$

Step 2: Introducing βx_{t-1}

- Add and subtract βx_{t-1} on the right-hand side:

$$\Delta y_t = \beta \Delta x_t - (y_{t-1} - \beta x_{t-1}) + u_t.$$

- This isolates the error correction term $y_{t-1} - \beta x_{t-1}$.

Now substitute $\Delta x_t = \gamma \Delta x_{t-1} + \nu_t$ into the equation:

$$\Delta y_t = \beta(\gamma \Delta x_{t-1} + \nu_t) - (y_{t-1} - \beta x_{t-1}) + u_t.$$

Step 3: Final Expression

- Distribute β in the equation:

$$\Delta y_t = \underbrace{\beta\gamma}_{\gamma_1} \Delta x_{t-1} - \underbrace{1}_{\delta} (y_{t-1} - \beta x_{t-1}) + \underbrace{(\beta\nu_t + u_t)}_{e_t}.$$

- Recognizing the key components:

$$\gamma_1 = \beta\gamma, \quad \delta = -1, \quad e_t = \beta\nu_t + u_t.$$

$$y_{t-1} > x_{t-1}$$

- Thus, we obtain the final error correction model:

$$\Delta y_t = \underbrace{\gamma_1}_{I(0)} \Delta x_{t-1} + \underbrace{\delta}_{LT} \underbrace{(y_{t-1} - \beta x_{t-1})}_{\leftarrow y_t = \beta x_t + u_t} + e_t.$$

$$X_c \sim I(1)$$

$$Y_c \sim I(1)$$

$$Y_c = \alpha + \beta X_c + u_c$$

$$\Delta Y_c = \alpha + \beta \Delta X_c$$

$$u_c = Y_c - \alpha - \beta X_c$$

↓
DF